**Command list:**

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Identifier: | Description: | R/W: | Format: | Range: | Units: |
| ? | Shows all the current states | R |  |  | / |
| P\_target= | Moves the motor for panning to a given degree | W |  |  | Degrees |
| p\_target? | Gives you the last given target fort he pan motor in degrees | R |  |  | / |
| t\_target= | Moves the motor for tilting to a given degree | W |  |  | Degrees |
| t\_target? | Gives you the last given target fort he tilt motor in degrees | R |  |  | / |
| p\_pos? | Gives you the current position of the pan motor in degrees | R |  |  | / |
| t\_pos? | Gives you the current position of the pan motor in degrees | R |  |  | / |
| pos? | Gives you the current positions of the pan and tilt motor in degrees | R |  |  | / |
| p\_stop | Stops the pan motor | W |  |  | / |
| t\_stop | Stops the tilt motor | W |  |  | / |
| stop | Stops both motors | W |  |  | / |
| p\_accel= | Changes the acceleration of the pan motor | W |  |  | Degrees/second^2 |
| t\_accel= | Changes the acceleration of the tilt motor | W |  |  | Degrees/second^2 |
| p\_max\_speed= | Changes the maximum speed of the pan motor | W |  |  | Degrees/second |
| t\_max\_speed= | Changes the maximum speed of the tilt motor | W |  |  | Degrees/second |
| p\_max\_speed? | Shows you the current maximum speed of the pan motor | R |  |  | / |
| t\_max\_speed? | Shows you the current maximum speed of the tilt motor | R |  |  | / |
| p\_enable= | Enables or unenables the motors | W |  | 0-1 | / |
| p\_enable? | Shows you if the motors are enabled or not | R |  |  | / |
| panHome | Sets the pan motor to its homing position | W |  |  | / |
| panHome? | Shows you if the pan motor is homed. | R |  |  | / |
| tilthome | Sets the tilt motor to its homing position | W |  |  | / |
| tiltHome? | Shows you if the tilt motor is homed. | R |  |  | / |